

P-611.3 NanoCube® XYZ Piezo Stage **Compact Multi-Axis Piezo System for Nanopositioning and Fiber Alignment**



- Up to 120 x 120 x 120 μm Travel Range
- Very Compact: 44 x 44 x 44 mm
- Resolution to 0.2 nm, Rapid Response
- Frictionless, High-Precision Flexure Guiding System
- **Outstanding Lifetime Due to PICMA® Piezo Actuators**
- Fast Multi-Axis Scanning
- Version with Integrated Fiber Adapter Interface
- Cost-Effective Mechanics/Electronics System Configurations

The P-611 NanoCube[®] piezo stage is a versatile, multi-axis piezo-nanopositioning system. Its 100 x 100 x 100 µm positioning and scanning range comes in an extremely compact package of only 44 x 44 x 44 mm. Equipped with a stiff, zero-stiction, zero-friction guiding system, this NanoCube® provides motion with ultra-high resolution and settling times of only a few milliseconds. The minimal .0r moved masses and the stiff for data sheets is available **Application Examples** Photonics / integrated

- optics Micromanipulation
- Biotechnology
- Semiconductor testing
- Fiber positioning

piezo drive make it ideal for high-throughput applications such as fiber alignment where it enables significantliy faster device characterization than achievable with conventional motorized drives.

Closed-Loop and Open-Loop Versions

High-resolution, fast-responding, strain gauge sensors (SGS) are applied to appropriate locations on the drive train and provide a high-bandwidth, nanometer-precision position feedback signal to the controller. The sensors are connected in a full-bridge configuration to eliminate thermal drift, and assure optimal position stability in the nanometer range.

The open-loop models are ideal for applications where fast response and very high resolution are essential, but absolute

positioning is not important, e.g. in tracking or fiber positioning. They can also be used when the position is controlled by an external linear position sensor such as an interferometer, a PSD (position sensitive diode), CCD chip / image processing system, or the eyes and hands of an operator.

Versatility & Combination with Motorized Stages

The P-611 family of piezo stages comprises a variety of singleand multi-axis versions (X, XY, Z, XZ and XYZ) that can be easily combined with a number of very compact manual or motorized micropositioning systems to form coarse/fine positioners with longer travel ranges (see p. 2-20, p. 2-36 and p. 2-50). For fiber positioning tasks, several fiber, waveguide and optics adapters are available for mounting on the NanoCube® P-611.3SF (e.g. for combination with the F-206.S nanoalignment system see p. 4-12).

High Reliability and Long Lifetime

The compact P-611 systems are equipped with preloaded

Ordering Information

P-611.3S

NanoCube[®] XYZ Nanopositioning System, 100 x 100 x 100 µm, Strain Gauge Sensors

P-611.30

NanoCube® XYZ Nanopositioning System, 100 x 100 x 100 µm, Open-Loop

P-611.3SF

NanoCube[®] XYZ Nanopositioning System, 100 x 100 x 100 µm, Strain Gauge Sensors, Fiber Adapter Interface

P-611.30F

NanoCube[®] XYZ Nanopositioning System, 100 x 100 x 100 µm, Open-Loop, Fiber Adapter Interface

PICMA® high-performance piezo actuators which are integrated into a sophisticated, FEA-modeled, flexure guiding system. The PICMA® actuators feature cofired ceramic encapsulation and thus offer better performance and reliability than conventional piezo actuators. Actuators, guidance and sensors are maintenance-free and not subject to wear, and thus offer an extraordinary reliability.



to change without notice. All data are superseded by any new release

Subject 1





Technical Data

Model	P-611.3S P-611.3SF	P-611.30 P-611.30F	Units	Tolerance
Active axes	X, Y, Z	X, Y, Z		
Motion and positioning				
Integrated sensor	SGS			
Open-loop travel, -20 to +120 V	120 / axis	120 / axis	μm	min. (+20 %/0 %)
Closed-loop travel	100 / axis	-	μm	
Open-loop resolution	0.2	0.2	nm	typ.
Closed-loop resolution	1	-	nm	typ.
Linearity	0.1	-	%	typ.
Repeatability	<10	-	nm	typ.
Pitch in X,Y	±5	±5	µrad	typ.
Runout θ_X (Z motion)	±10	±10	µrad	typ.
Yaw in X	±20	±20	µrad	typ.
Yaw in Y	±10	±10	µrad	typ.
Runout θ_{Y} (Z motion)	±10	±10	µrad	typ.
Mechanical properties				
Stiffness	0.3	0.3	N/µm	±20%
Unloaded resonant frequency X / Y / Z	350 / 220 / 250	350 / 220 / 250	Hz	±20%
Resonant frequency @ 30 g X / Y / Z	270 / 185 / 230	270 / 185 / 230	Hz	±20%
Resonant frequency @ 100 g X / Y / Z	180 / 135 / 200	180 / 135 / 200	Hz	±20%
Push/pull force capacity in motion direction	+15 / -10	+15 / -10	N	Max.
Load capacity	15	15	Ν	Max.
Drive properties				
ceramic type	PICMA [®] P-885	PICMA® P-885		
Electrical capacitance	1.5	1.5	μF	±20%
Dynamic operating current coefficient	1.9	1.9	μΑ/(Hz • μm)	±20%
Miscellaneous				
Operating temperature range	-20 to 80	-20 to 80	°C	
Material	Aluminum, steel	Aluminum, steel		
Dimensions	44 x 44 x 43.2 SF-version: 44 x 50 x 44.2	44 x 44 x 43.2 OF-version: 44 x 50 x 44.2	mm	
Mass	0.32	0.32	kg	±5%
Cable length	1.5	1.5	m	±10 mm
Sensor connector	Sub-D	-		
Voltage connection	Sub-D	Sub-D		
Recommended controller / amplifier	E-664 Nanocube® Controller (p. 2-137)	3 x E-610.00F OEM amplifier modules (p. 2-110); E-663 3-channel amplifier, bench-top (p. 2-136)		

Resolution of PI Piezo Nanopositioners is not limited by friction or stiction. Value given is noise equivalent motion with E-503 amplifier (p. 2-146) Dynamic Operating Current Coefficient in µA per Hz and µm. Example: Sinusoidal scan of 50 µm at 10 Hz requires approximately 0.8 mA drive current. Adapter cable with LEMO connectors for sensor and operating voltage available.